

A Multi-step-ahead Markov Conditional Forward Model with Cube Perturbations For Extreme Weather Forecasting

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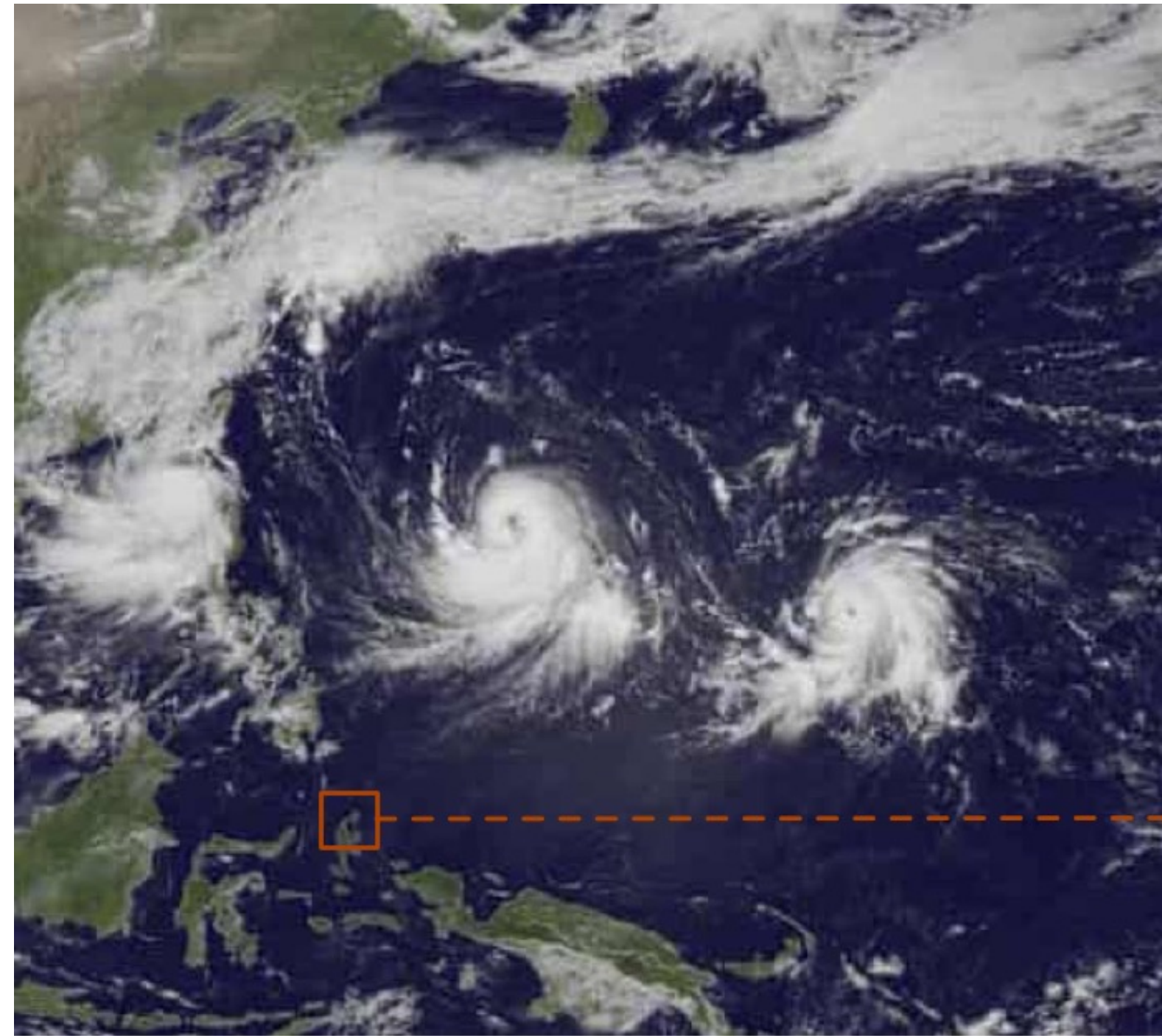
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ACADEMIA SINICA

Agenda

- Introduction
- MSA Prediction Model
- Cube Perturbation
- Experiment Results
- Conclusion

Introduction

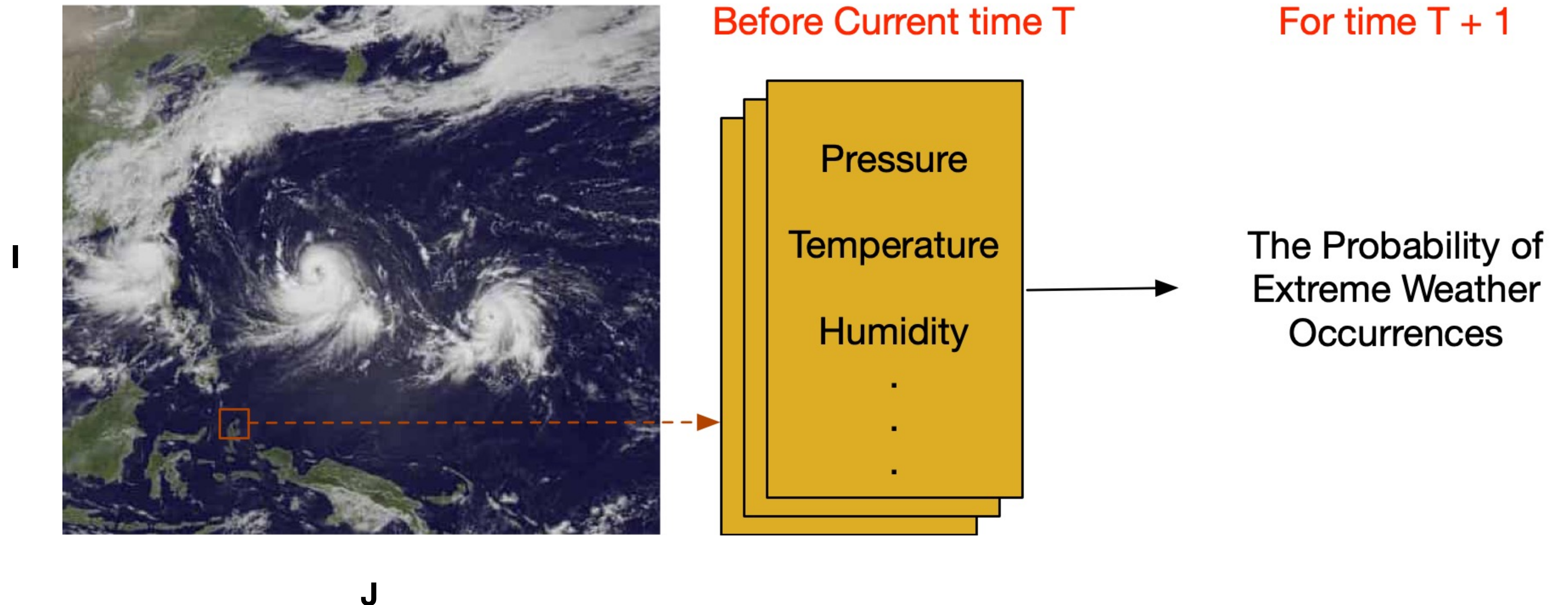
- Goal : Predict extreme weather at future horizons (time stamps).
- Multi-step-ahead (MSA) Prediction.



Will Extreme
Weather Happens
Here 1 day later?

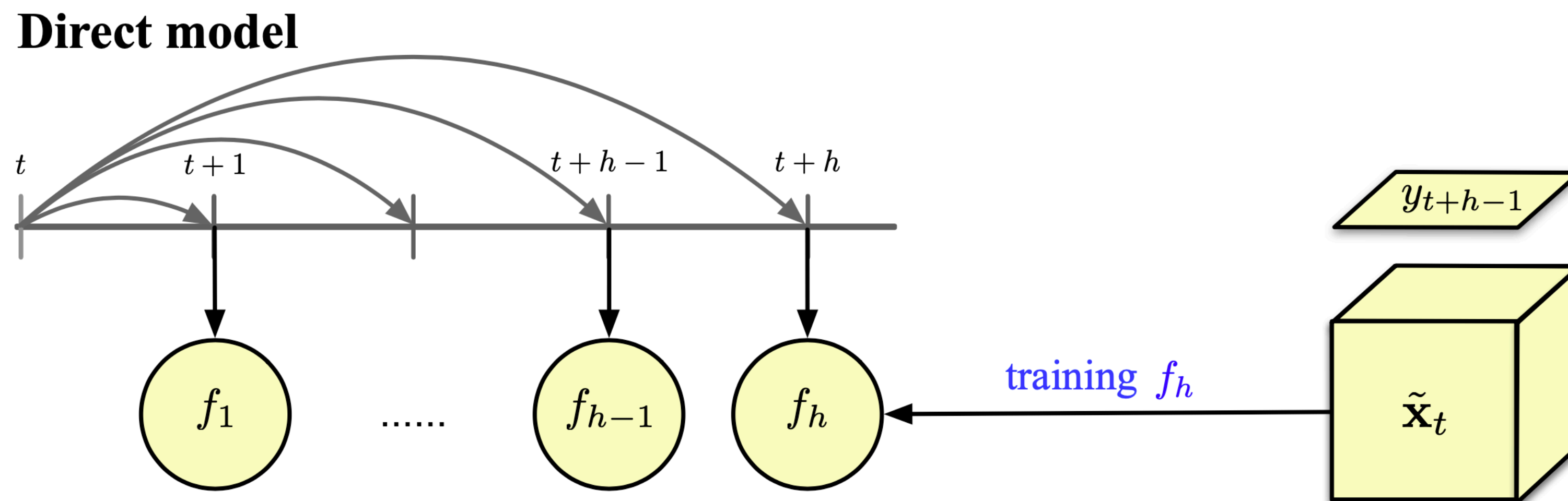
Introduction

- What we have : weather features (channels) in the past.



MSA Prediction Model

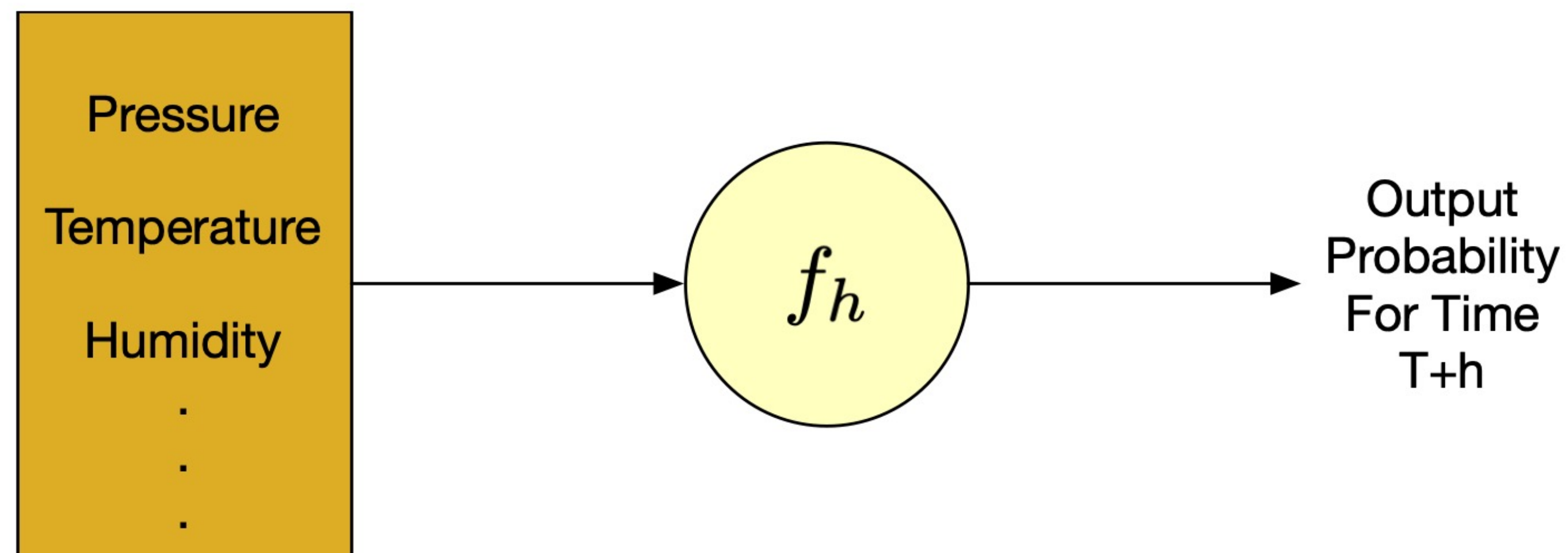
- **Direct Model** : it treats each future prediction time point independently and build a model for each of them



MSA Prediction Model

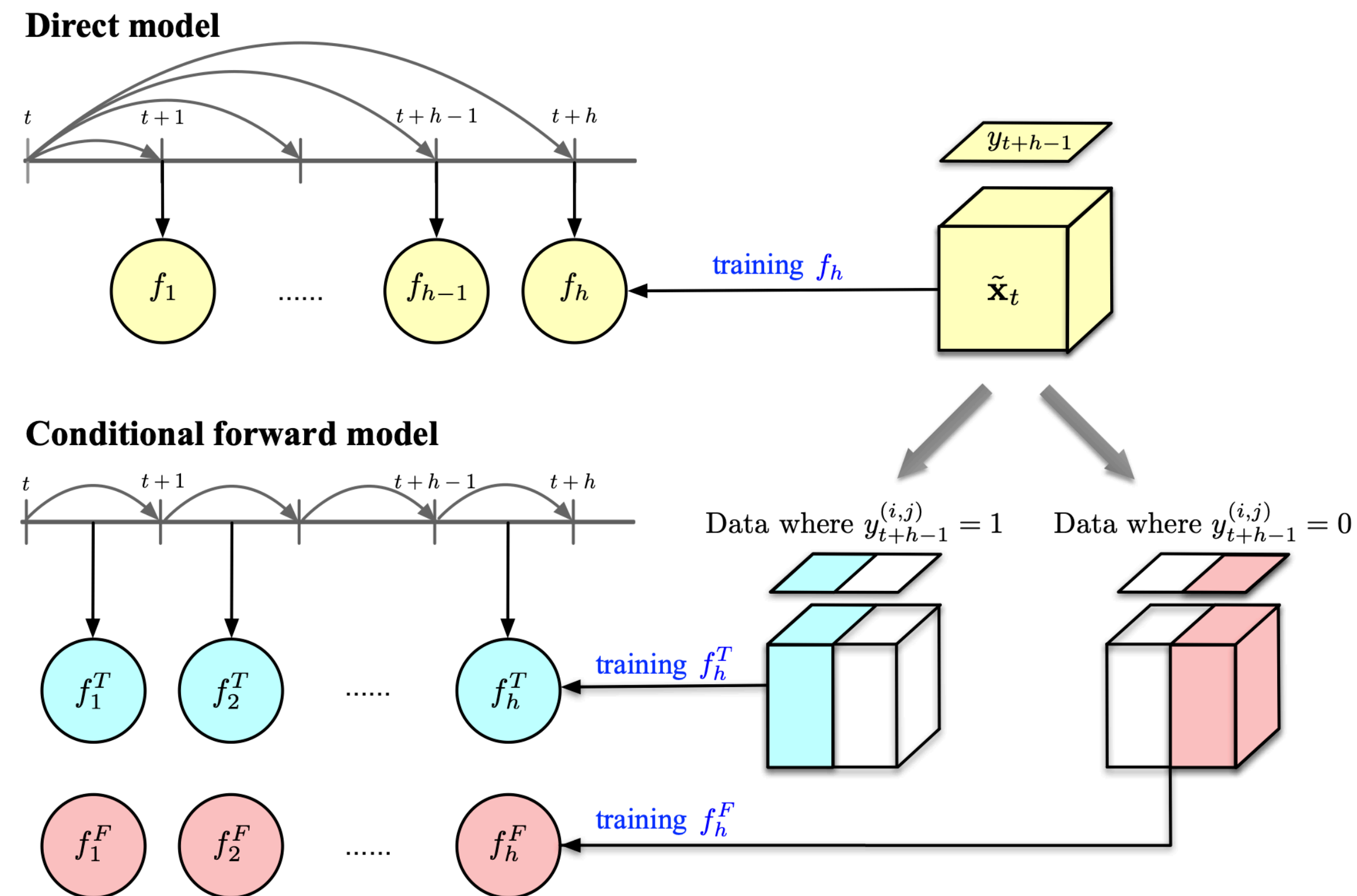
- **Direct Model** : if we want to predict the probability of extreme weather for $T+h$ (the current time is T), we just need to do the following :

At Current time T



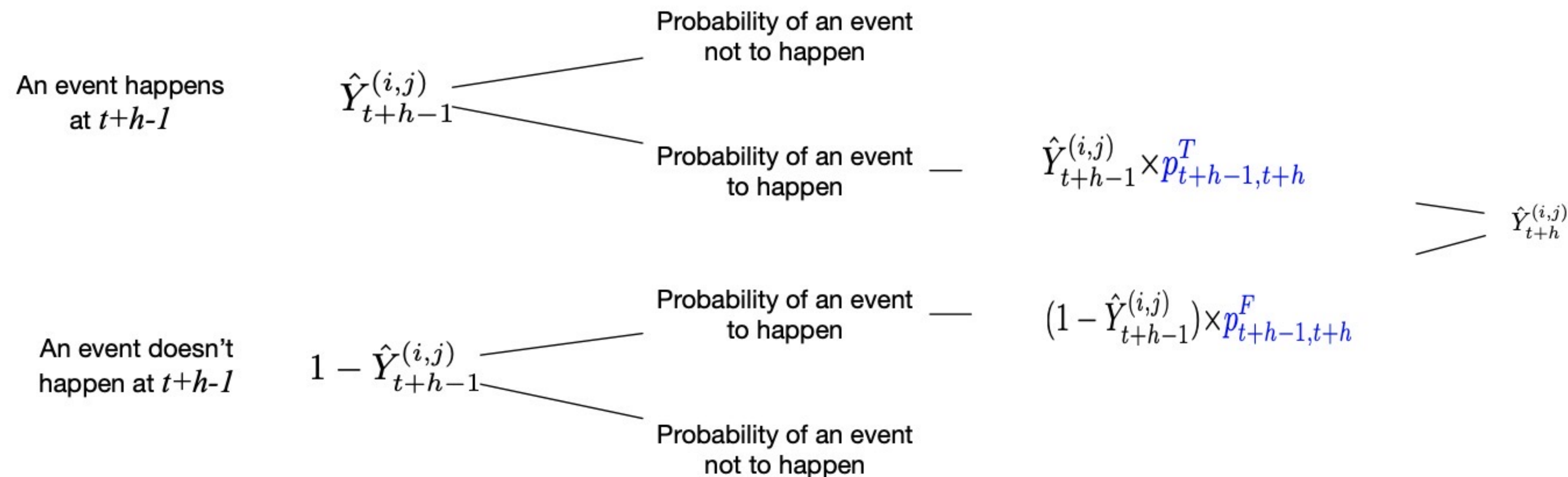
MSA Prediction Model

- Markov Conditional Forward Model (MCF): We build two models to calculate conditional probability between two consecutive prediction time and adopt Markov Probability to do probability inference.



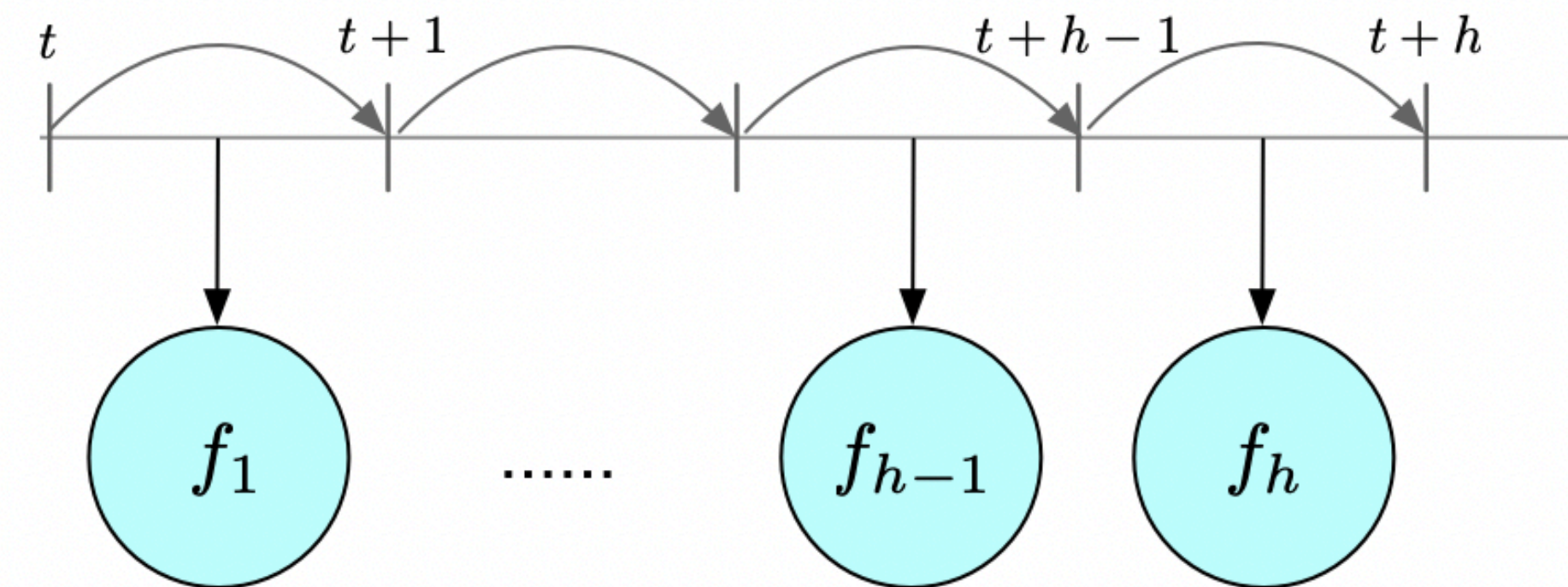
MSA Prediction Model

- Markov Conditional Forward Model (MCF) : if we want to predict the probability of extreme weather for $T+h$ by inferencing using the probability at $T+h-1$, we need to do the following inference:



Cube Perturbation

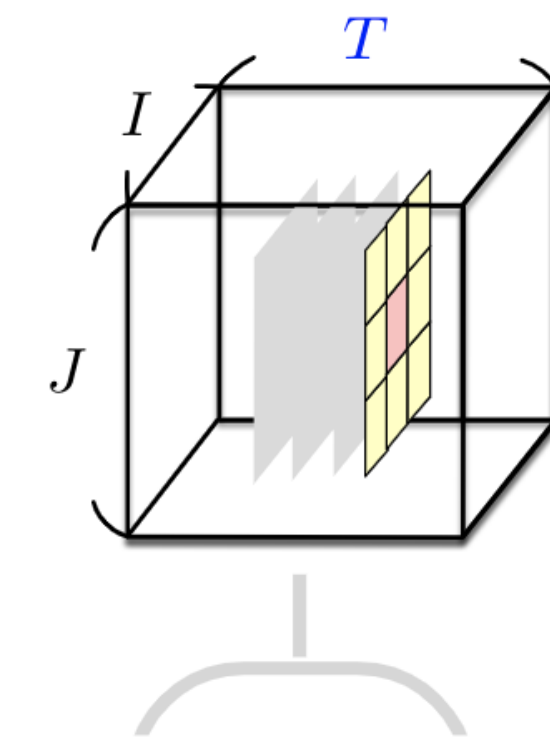
- To address error accumulation
 - MCF model accumulates error because of using predicted values to compute the next prediction.



- Naïve Perturbation
 - Randomly switch the label from 0 to 1 (or from 1 to 0) based on a predefined probability.

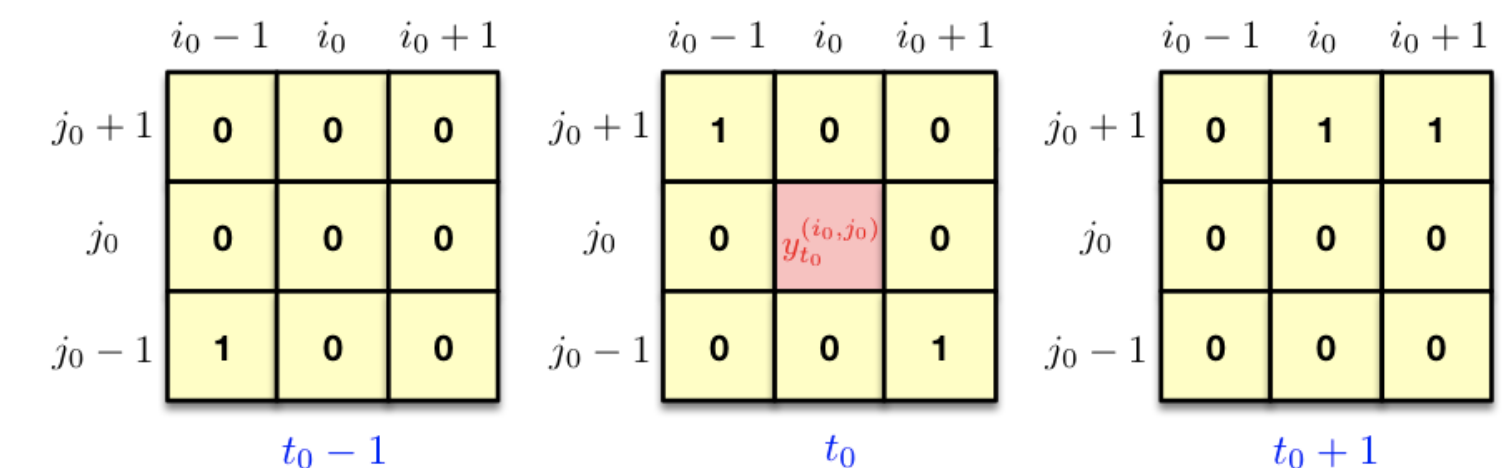
Cube Perturbation

- Two assumptions of cube perturbations
 - Positive data are more critical for model training than negative data because of their sparsity.
 - Spatial and temporal correlations among labels in the obtained data exist.



- The definition of “Cube” (or “Neighbor”)

$$\mathcal{N}_{t_0}^{(i_0, j_0)} = \{(i, j, t) \mid i \in \mathcal{I} \wedge j \in \mathcal{J} \wedge t \in \mathcal{T} \wedge |i - i_0| \leq \kappa \wedge |j - j_0| \leq \kappa \wedge |t - t_0| \leq \kappa\} \setminus \{(i_0, j_0, t_0)\}$$



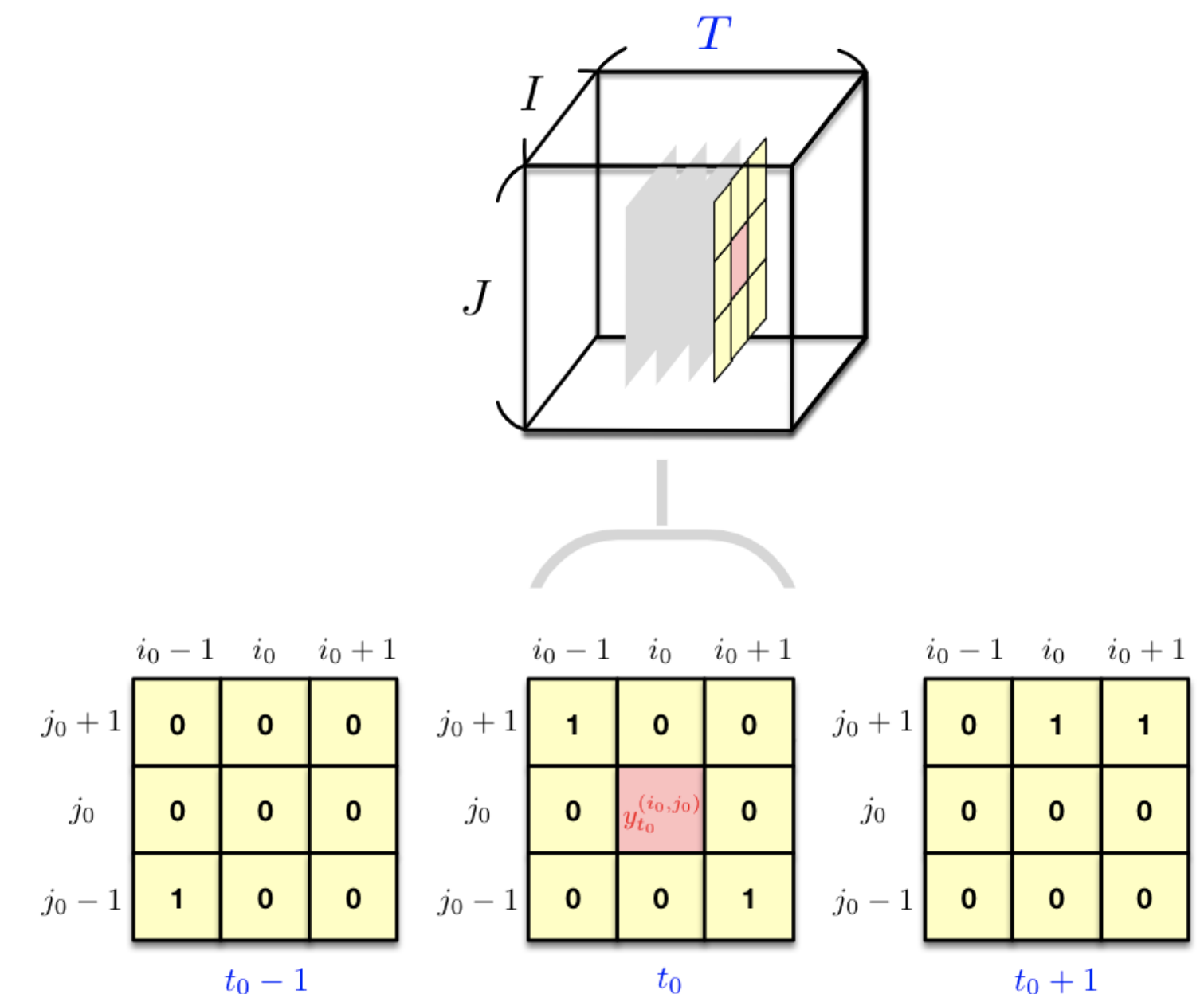
- E.g., $\kappa = 1$ results in a $3 \times 3 \times 3$ cube perturbation.

Cube Perturbation

- Simple Cube Perturbation (SCP)

- Based on the aforementioned two assumptions:

$$y_{t_0}^{(i_0, j_0)} \neq 1 \wedge \exists (i, j, t) \in \mathcal{N}_{t_0}^{(i_0, j_0)} \left(y_t^{(i, j)} = 1 \right)$$



Cube Perturbation

- Neighborhood Probability Cube Perturbation (NPCP)
 - The perturbation probability is proportional to how many of its neighbors have positive labels

$$\xi_{(i_0, j_0, t_0)}^{\text{NPCP}} = \frac{\left| \left\{ (i, j, t) \mid (i, j, t) \in \mathcal{N}_{t_0}^{(i_0, j_0)} \wedge y_t^{(i, j)} = 1 \right\} \right|}{\left| \mathcal{N}_{t_0}^{(i_0, j_0)} \right|}$$

Cube Perturbation

- **Multinomial Cube Perturbation (MCP)**

- Models the probability of counts for each side of a k-sided die rolled n times.

$$\xi_{(i_0, j_0, t_0)}^{\text{MCP}} = \frac{\left| \left\{ (i, j, t) \mid (i, j, t) \in \mathcal{N}_{t_0}^{(i_0, j_0)} \wedge y_t^{(i, j)} = 1 \right\} \right|}{\sum_{\forall \hat{i}, \hat{j}, \hat{t}} \left| \left\{ (i, j, t) \mid (i, j, t) \in \mathcal{N}_{\hat{t}}^{(\hat{i}, \hat{j})} \wedge y_t^{(i, j)} = 1 \right\} \right|}$$

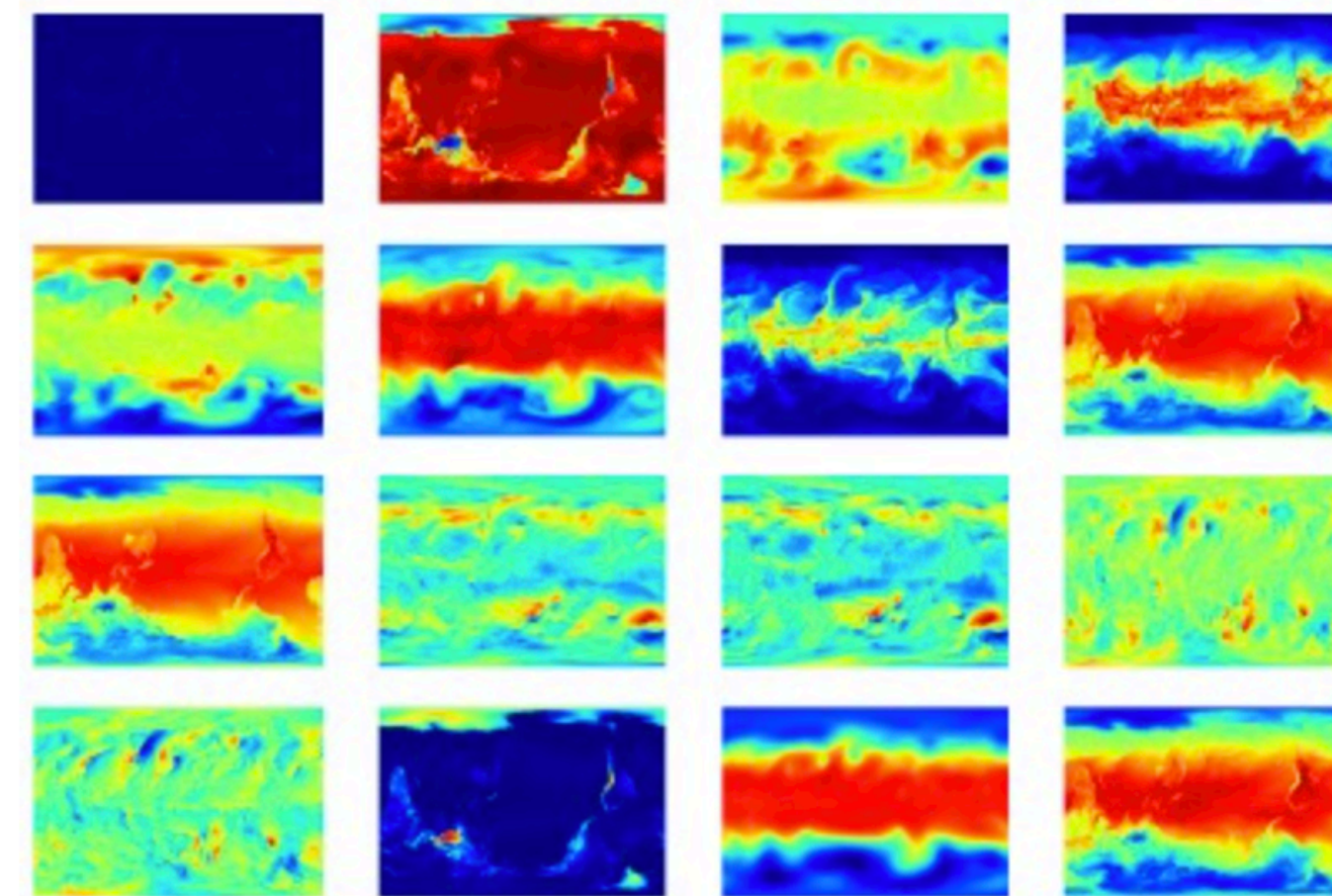
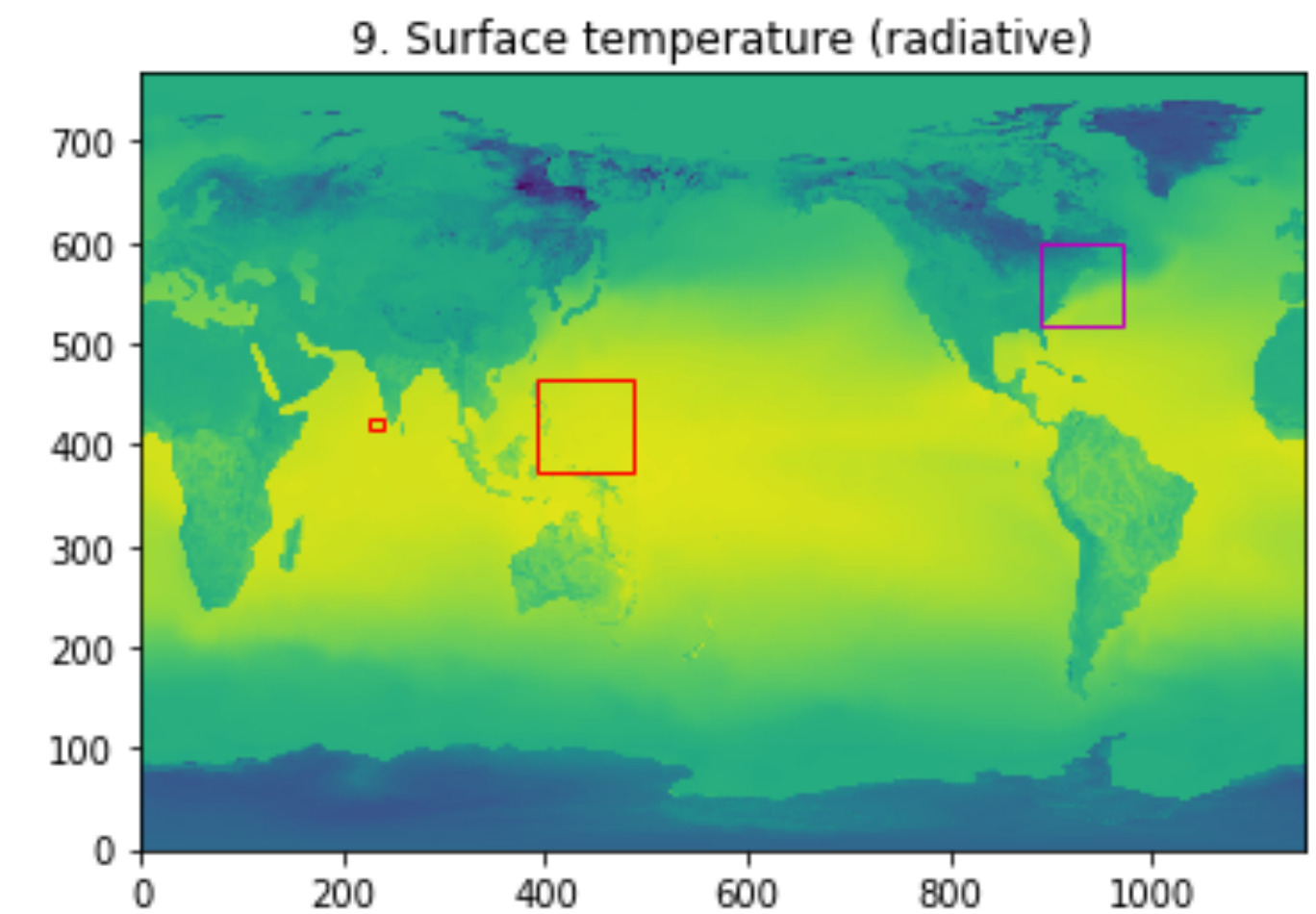
- We then roll the k-sided die n times to obtain n data points for perturbation, where n is associated with:

$$r^{\text{MCP}} = n/k \quad \text{with } k = I \times J \times T$$

Experiment Results

● Datasets: ExtremeWeather

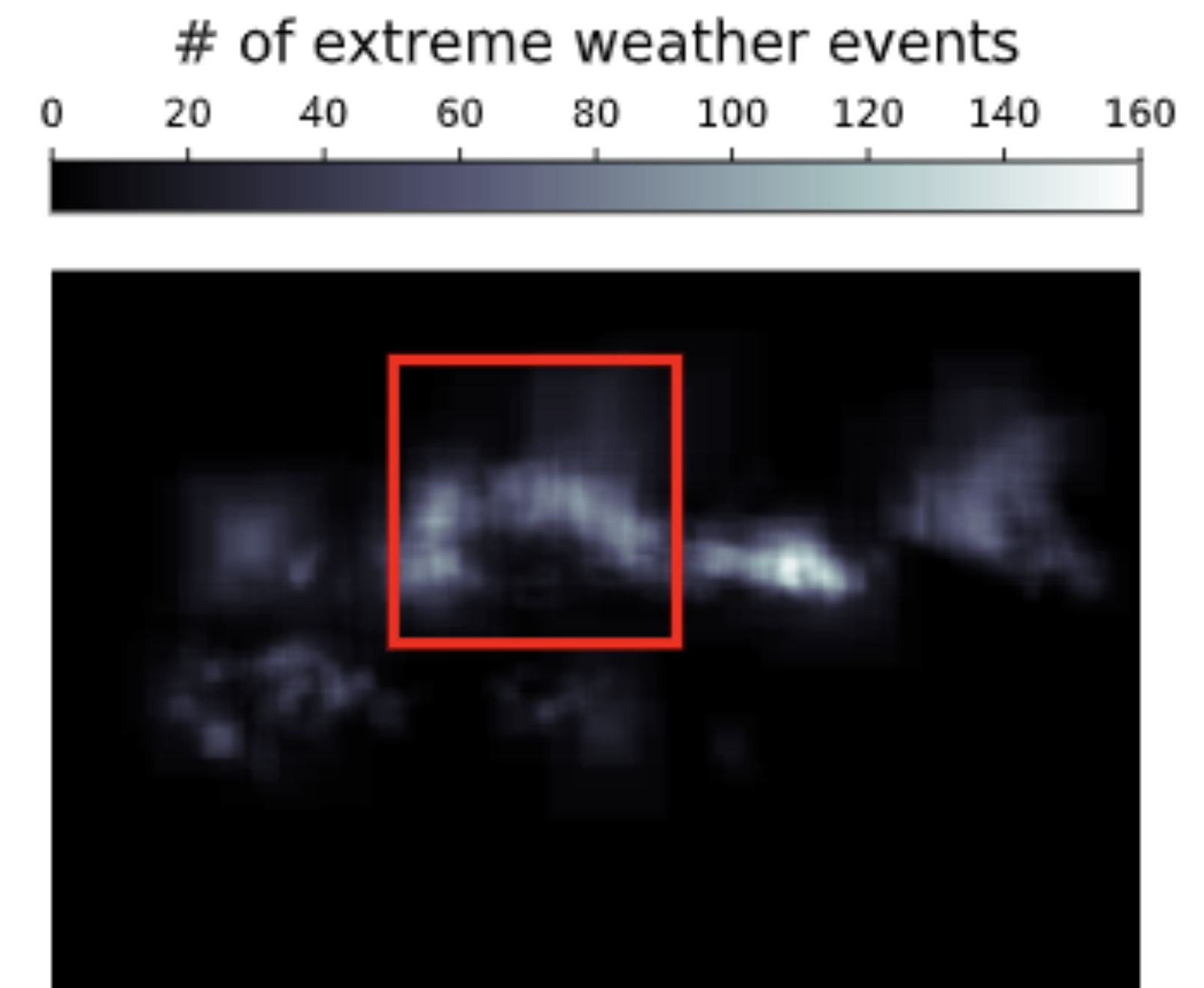
- A physical variables image dataset containing extreme weather labels in each temporal resolution
- 16 channels (e.g. pressure, temperature, humidity...)
- Each horizon is equal to 6 hours
- 4 labels of extreme weather



Experiment Results

● Experiment Setting

- Two extreme weather phenomena
 - Tropical cyclone
 - Extratropical cyclone
- Conducted experiments in a certain area
 - 150 x 150 most active area
 - 50 - km resolution



Experiment Results

- Direct and MCF model performance (AUC)

Tropical cyclones									
Horizons (hours)	6	12	18	24	30	36	42	48	Average
LR (direct)	0.6682	0.6664	0.6641	0.6490	0.6472	0.6502	0.6576	0.6428	0.6557
LR (MCF)	0.7376	0.7213	0.7081	0.6747	0.6598	0.6634	0.6567	0.6428	0.6830
LR improvement (%)	10.39**	8.25**	6.63**	3.96**	1.93**	2.04**	-0.14*	0.00	4.16
CNN (direct)	0.6760	0.6760	0.6773	0.6629	0.6577	0.6601	0.6674	0.6518	0.6662
CNN (MCF)	0.7441	0.7309	0.7188	0.6864	0.6739	0.6756	0.6689	0.6506	0.6937
CNN improvement (%)	10.07**	8.12**	6.13**	3.55**	2.46**	2.35**	0.22	-0.18	4.13
Extratropical cyclones									
Horizons (hours)	6	12	18	24	30	36	42	48	Average
LR (direct)	0.8243	0.8113	0.7976	0.7831	0.7628	0.7429	0.7303	0.7242	0.7721
LR (MCF)	0.9361	0.8858	0.8426	0.8104	0.7821	0.7564	0.7376	0.7275	0.8098
LR improvement (%)	13.56**	9.19**	5.64**	3.48**	2.53**	1.81**	1.00**	0.46**	4.88
CNN (direct)	0.8244	0.8119	0.7979	0.7843	0.7734	0.7614	0.7489	0.7396	0.7802
CNN (MCF)	0.9360	0.8851	0.8421	0.8103	0.7852	0.7651	0.7532	0.7413	0.8148
CNN improvement (%)	13.54**	9.02**	5.54**	3.32**	1.53**	0.49**	0.57**	0.23**	4.43

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Experiment Results

- Performance of various perturbation methods (AUC)

Tropical cyclones									
Horizons (hours)	6	12	18	24	30	36	42	48	Average
CNN (MCF)	0.7441	0.7309	0.7188	0.6864	0.6739	0.6756	0.6689	0.6506	0.6937
+Naive ($\xi^{\text{Naive}} = 5\%$)	0.7405	0.7144	0.6898	0.6614	0.6551	0.6555	0.6602	0.6438	0.6776
+Multinomial cube ($r^{\text{MCP}} = 10\%$)	0.7395	0.7266	0.7182	0.6863	0.6749	0.6791	0.6678	0.6481	0.6926
+Simple Cube ($\xi^{\text{SCP}} = 47.5\%$)	0.7458	0.7317	0.7266	0.6999	0.6908	0.7045	0.6820	0.6633	0.7056
+Neighborhood prob cube	0.7445	0.7308	0.7272	0.7002	0.6922	0.7077	0.6846	0.6668	0.7068
Improvement (%)	0.23	0.11	1.16*	2.01*	2.71**	4.76**	2.35*	2.48*	1.89
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+Naive ($\xi^{\text{Naive}} = 2.5\%$)	0.9371	0.8808	0.8288	0.7957	0.7716	0.7566	0.7470	0.7385	0.8070
+Multinomial cube ($r^{\text{MCP}} = 5\%$)	0.9365	0.8861	0.8425	0.8105	0.7857	0.7661	0.7545	0.7435	0.8157
+Simple Cube ($\xi^{\text{SCP}} = 47.5\%$)	0.9356	0.8855	0.8428	0.8101	0.7845	0.7663	0.7558	0.7442	0.8156
+Neighborhood prob cube	0.9368	0.8873	0.8444	0.8112	0.7849	0.7650	0.7538	0.7428	0.8158
Improvement (%)	0.12	0.24	0.27	0.12	0.06	0.16	0.35	0.39	0.12

Experiment Results

- Performance of various perturbation methods (AUC)

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Improvement (%)	0.12	0.24	0.27	0.12	0.06	0.16	0.35	0.39	0.12

Conclusion

- **MCF model** provides better performance than traditional direct model on **MSA extreme weather prediction**.
- MCF model learned with **the use of CNN** yields prominent results for **both short-term and long-term** predictions.
- **Cube perturbation** methods successfully enhance the fault tolerance of the MCF model by **addressing error accumulation**.

Thanks For Your Listening! Any Question?