HOP-Rec

High-Order Proximity for Implicit Recommendation

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Recommender Systems are software tools and techniques providing suggestions for items to be of use to a user



Francesco, R., R. Lior, and S. Bracha. "Introduction to Recommender Systems Handbook, Recommender Systems Handbook." (2011).



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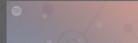
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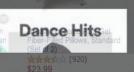












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Collaborative Filtering

Make
predictions
by collecting
preference
information
from users

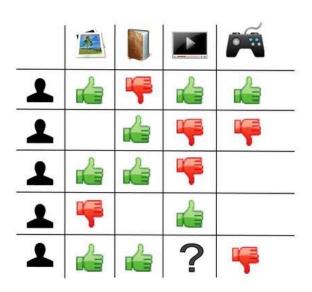


Figure: https://www.youtube.com/watch?v=FSKIoPyIEkM

Collaborative Filtering

Latent Factor Model

Discover shared latent factors between users and items by decomposing user-item interaction matrix



Graph-based Model

Explore the **relationships** between users and items within a **graph structure**

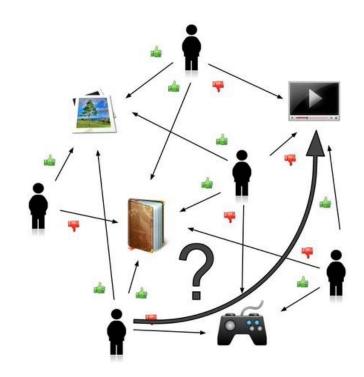


Figure: https://en.wikipedia.org/wiki/Collaborative_filtering

Related Works

Latent Factor Model

- Matrix Factorization (MF)
- Bayesian Personalized Ranking (BPR)
- Weighted Approximate-Rank Pairwise (WARP) loss
- K-Order Statistic (K-OS) loss

Pointwise

Pairwise

User-Item interaction matrix

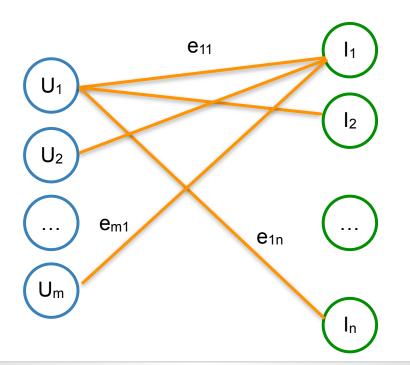
User latent factors

Item latent factors

Related Works

Graph-based Model

- PageRank
- ItemRank
- S-step random walk distribution (hitting time)
- Popularity-based Re-ranking (RP³(β)) (transition probability)



Motivation

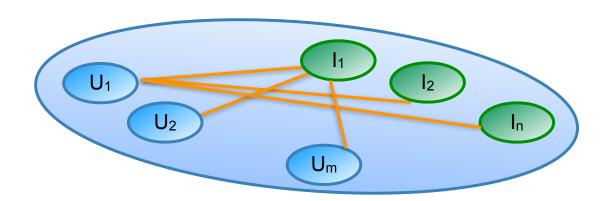
Motivation: Problem

Latent Factor Model

Only discriminate shallow observations within user-item interaction

Graph-based Model

 Explore higher-order proximities within graph, but unreached item will not be affect remotely

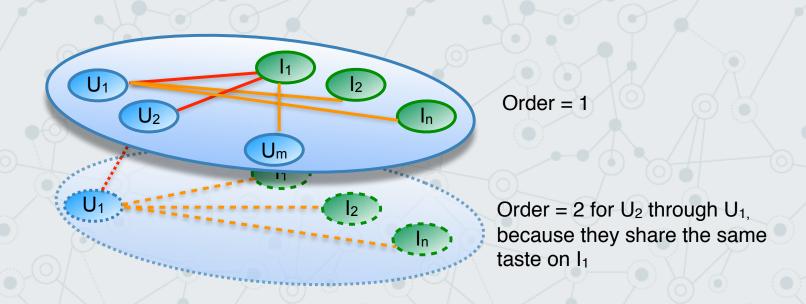


Park, Haekyu, Jinhong Jung, and U. Kang. "A comparative study of matrix factorization and random walk with restart in recommender systems." *Big Data (Big Data), 2017 IEEE International Conference on.* IEEE, 2017.

Motivation: Hybrid

HOP-Rec = Latent Factor Model + Graph-based model

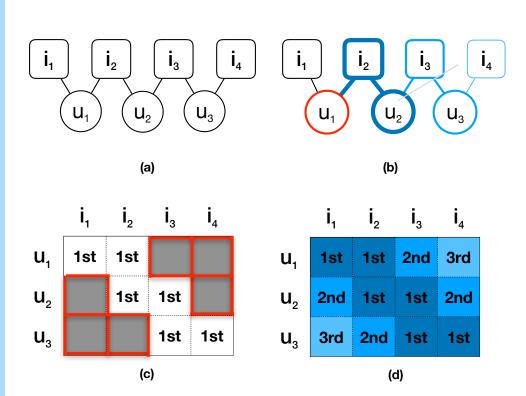
- Order-aware objectives
- Latent factor based



Motivation: Assumption

Assumptions:

- The preference of unknown items could be estimated from indirect observations.
- The estimation should be ordered by the neighborhood proximities.



Model: Methodology

Objective function

Hybrid

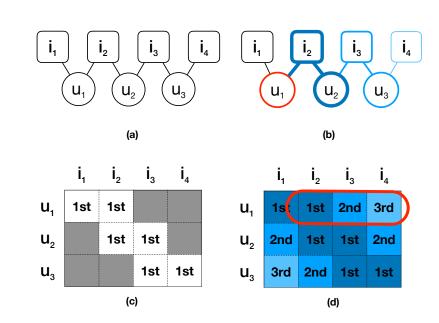
$$\mathcal{L}_{HOP} = \sum_{\substack{1 \leq k \leq K \\ u.(i.i')}} \underbrace{\mathcal{C}(k) \mathbb{E}_{i \sim P_u^k}}_{i' \sim P_N} \underbrace{\mathcal{F}(\theta_u^{\mathsf{T}} \theta_{i'}, \theta_u^{\mathsf{T}} \theta_i)}_{+\lambda_{\Theta}} \|\Theta\|_2^2$$

Pairwise

$$\mathcal{F}(\theta_u^{\mathsf{T}}\theta_{i'}, \theta_u^{\mathsf{T}}\theta_i) = \mathbb{1}_{\{\theta_u^{\mathsf{T}}\theta_{i'} - \theta_u^{\mathsf{T}}\theta_i > \epsilon_k\}} \log \left[\sigma \left(\theta_u^{\mathsf{T}}\theta_{i'} - \theta_u^{\mathsf{T}}\theta_i\right)\right]$$

Optimization Flow

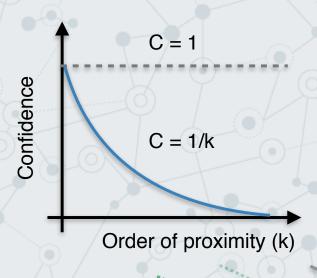
- Sample path on graph
- Optimize pairwise relationship between positive and negative items of different orders



Three Stories

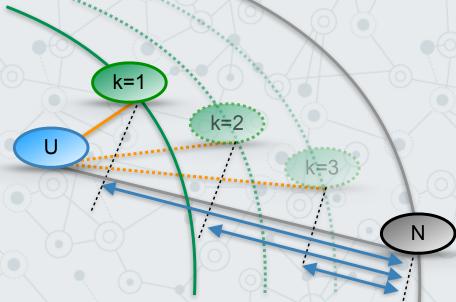
Model: Details

Confidence model



$$\mathcal{L}_{HOP} = \sum_{\substack{1 \leq k \leq K \\ u, (i, i')}} \underbrace{\overline{\mathcal{C}(k)} \mathbb{E}_{\substack{i \sim P_u^k \\ i' \sim P_N}} \underbrace{[\mathcal{F}(\theta_u^{\mathsf{T}} \theta_{i'}, \theta_u^{\mathsf{T}} \theta_i)]}_{\text{factorization model}} + \lambda_{\Theta} \|\Theta\|_2^2$$

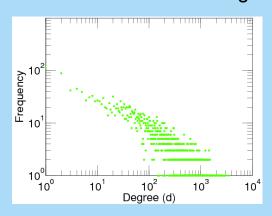
$$\mathcal{F}(\theta_u^{\intercal}\theta_{i'},\theta_u^{\intercal}\theta_i) = \mathbb{1}_{\{\theta_u^{\intercal}\theta_{i'}-\theta_u^{\intercal}\theta_i\} \in \mathbf{k}} \log\left[\sigma\left(\theta_u^{\intercal}\theta_{i'}-\theta_u^{\intercal}\theta_i\right)\right]$$

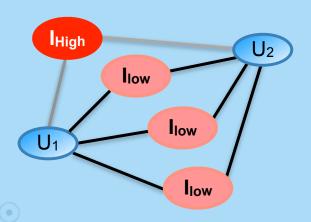


 Items discovered at different order should be distinguished from other negative items

Model: Details

Movielens-1M: Movie degree





Degree Sampling

- For each user, probability of sampling paths with high degree items will be low
- Balanced by increase probability of sampling high degree items

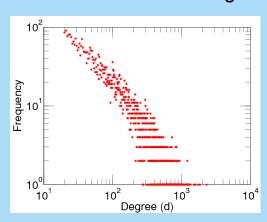
$$\mathcal{L}_{HOP} = \sum_{\substack{1 \leq k \leq K \\ u, (i, i')}} \underbrace{\mathcal{C}(k) \mathbb{E}_{i \sim P_u^k}}_{i' \sim P_N} \underbrace{\mathcal{F}\left(\theta_u^\intercal \theta_{i'}, \theta_u^\intercal \theta_i\right)}_{\text{factorization model}} + \lambda_{\Theta} \|\Theta\|_2^2$$

$$p_x^k(y) = \begin{cases} \frac{a_{xy}deg(y)}{\sum_{y'} a_{xy'}deg(y')} & \text{if } k = 1 \text{ and } x \in U, \\ \frac{a_{yx}deg(y)}{\sum_{y'} a_{y'x}deg(y')} & \text{if } k = 1 \text{ and } x \in I, \\ p_x^1(\alpha)p_\alpha^{k-1}(\beta)p_\beta^1(y) & \text{if } k > 1, \end{cases}$$

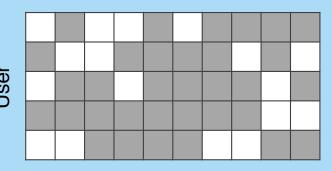
Christoffel, Fabian, et al. "Blockbusters and wallflowers: Accurate, diverse, and scalable recommendations with random walks." *Proceedings of the 9th ACM Conference on Recommender Systems*. ACM, 2015.

Model: Details

Movielens-1M: User degree



Item



Negative sampling

- For each user, most items are not rated (negative) rather rated (positive)
- We uniformly draw negative items from all items

$$\mathcal{L}_{HOP} = \sum_{\substack{1 \leq k \leq K \\ u, (i, i')}} \underbrace{\overbrace{\mathcal{C}(k) \mathop{\mathbb{E}}_{i \sim P_u^k}}_{i' \sim P_N}} \underbrace{\left[F\left(\theta_u^\intercal \theta_{i'}, \theta_u^\intercal \theta_i\right) \right]}_{+\lambda_{\Theta}} + \lambda_{\Theta} \left\|\Theta\right\|_{2}^{2}$$

Experiment: Implicit Feedback

To predict whether user U_m interact with item I_n

Datasets

Table 1: Datasets

Dataset	CiteUlike ^a	$\begin{array}{c} \text{MovieLens-} \\ 1\text{M}^{\text{b}} \end{array}$	$\begin{array}{c} \text{MovieLens-} \\ 20 \text{M}^{\text{b}} \end{array}$	Amazon- Book ^c
Users (U)	3,527	6,034	136,674	449,475
Items (I)	6,339	$3{,}125$	13,680	$292,\!65$
Feedback (E)	$77,\!546$	$574,\!376$	$9,\!977,\!451$	6,444,944
Density	0.347%	3.046%	0.534%	0.005%

a http://www.wanghao.in/data/ctrsr_datasets.rar

b https://grouplens.org/datasets/movielens

c http://jmcauley.ucsd.edu/data/amazon

Experiment: Evaluation

Performance comparison

Table 2: Performance comparison

	CiteUlike		MovieLens-1M		MovieLens-20M			Amazon-Book				
	P@10	R@10	MAP@10	P@10	R@10	MAP@10	P@10	R@10	MAP@10	P@10	R@10	MAP@10
MF	4.1%	13.1%	6.7%	17.7%	13.1%	11.7%	14.9%	14.0%	11.3%	0.7%	3.7%	1.4%
BPR	3.8%	14.2%	6.4%	18.1%	13.2%	12.5%	13.3%	14.3%	10.4%	1.0%	5.3%	2.5%
WARP	5.4%	18.3%	9.1%	24.8%	18.5%	18.5%	20.7%	21.4%	17.2%	1.4%	7.6%	3.2%
K-OS	5.6%	19.4%	9.5%	23.0%	17.3%	16.4%	19.6%	20.5%	15.7%	1.5%	7.9%	3.5%
$RP^3(\beta)$	5.9%	21.2%	3.2%	22.8%	17.2%	14.2%	17.3%	19.4%	10.3%	-	-	-
HOP	5.9%	21.3%	*10.8%	* 25.9 %	*20.5 %	*19.6%	*21.2 %	*22.3%	*1 7.9 %	1.5%	7.9%	*3.6%
%Improv.	0.0%	0.5%	13.7%	4.4%	10.8%	5.9%	2.4%	4.2%	4.1%	0.0%	0.0%	2.9%

Experiment: Evaluation

K-order sensitivity

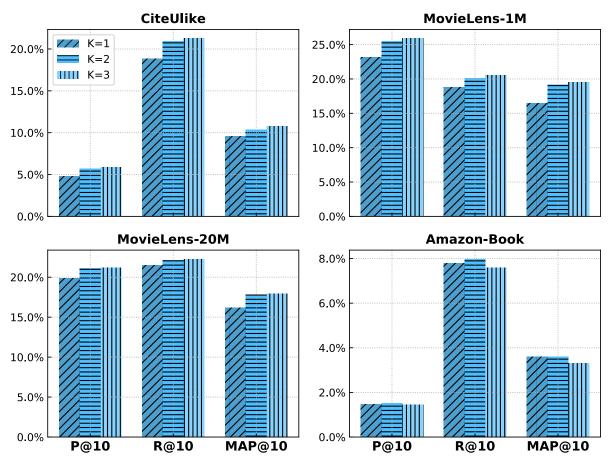


Figure 2: Sensitivity analysis with respect to *K*

Conclusion

Take-home Messages

- We demonstrate an approach that combines both representative CF-based methods
- High-order information within user-item interaction matrix is helpful for implicit recommendation



Conclusion

Future Works

- Conduct comprehensive study on walking strategies
- Extend HOP-Rec to explicit feedback problems
- Examine other metrics: diversity
- Develop more efficient negative sampling strategy
- Develop other forms of confidence model



Thanks! I am Jheng-Hong Yang

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DOI



CFDA & CLIP Labs



Source Code: ProNet



