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Multi-behavior Recommendation with Action Pattern-aware Networks

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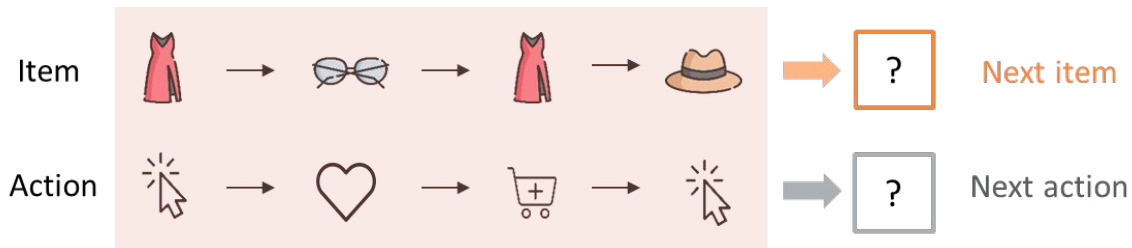


Problem Statement

Given a multiplex behavior session s , which contains

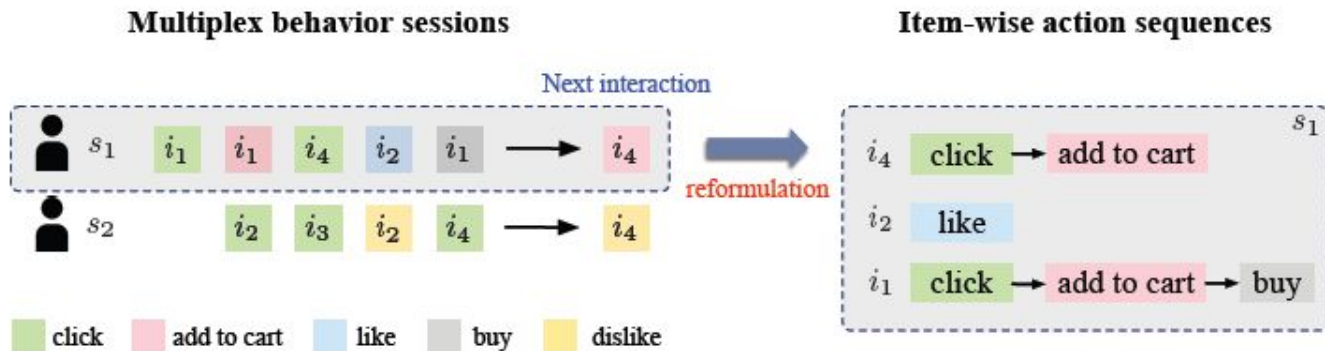
- ⊙ Item sequence $[i_1, \dots, i_t]$
- ⊙ Action sequence $[a_1, \dots, a_t]$

predict the next item \hat{i}_{t+1} and its corresponding next action \hat{a}_{t+1}



Motivations

- ⊙ Limitations of existing work
 - Concentrate on **single** action type of next item
 - Encode item and action sequences **separately** with similar algorithms



Contributions

- ◎ Propose an action-aware network multi-behavior recommender (APANet) to predict not only next item but also next action
- ◎ Identify the importance of modeling item-wise action sequences and propose a way to model such patterns
- ◎ Demonstrate effectiveness of methods in APANet by extensive experiments on three datasets

Notations

Given

- Session set \mathcal{S} , Item set $I = \{i_1, \dots, i_m\}$, Action set $A = \{a_1, \dots, a_n\}$

Define

- Session \mathcal{s} represented as index sequences $[(x_1, y_1), (x_2, y_2), \dots, (x_t, y_t)]$
 - $x_k \in \{1, 2, \dots, m\}, y_k \in \{1, 2, \dots, n\}$
 - $i_{x_k} \in I, a_{y_k} \in A$
- Action pattern set $B = \{b_1, b_2, \dots, b_n\}$, e.g. $b_1 = [a_1, a_2]$

i_2, i_3, i_2, i_2
 a_1, a_3, a_2, a_3

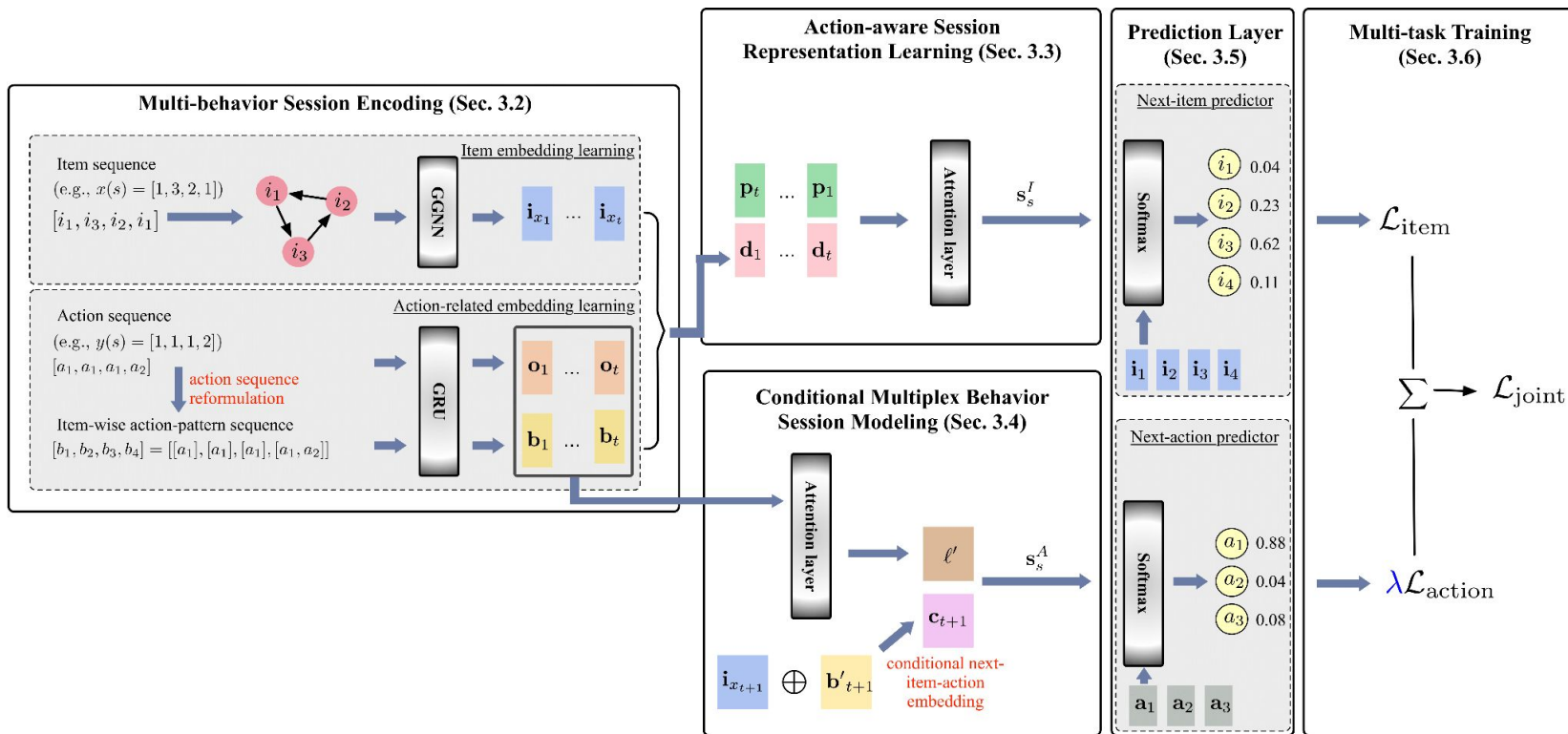
Action sequence



$i_2 \quad i_3 \quad i_2 \quad i_2$
 $[a_1] \quad [a_3] \quad [a_1, a_2] \quad [a_1, a_2, a_3]$

Action pattern (accumulated action sequence per item)

Model: APANet



Proposed Methods



Multi-behavior session encoding

Item embedding learning

Action-related embedding learning



Conditional multiplex behavior session modeling

Next action prediction given specific item



Action-aware session representation learning

Next item prediction considering the action pattern



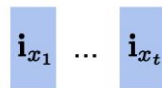
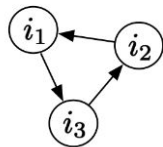
Multi-task learning

Optimize both item and action prediction simultaneously

Multi-behavior session encoding

Item embedding

Item sequence
(*ex.* $x(s) = [1, 3, 2, 1]$)
 i_1, i_3, i_2, i_1



Outgoing edges Incoming edges

	i_1	i_2	i_3	i_1	i_2	i_3
i_1	0	0	1	0	1	0
i_2	1	0	0	0	0	1
i_3	0	1	0	1	0	0

Connection matrix
 $A_s = (A^{out}, A^{in})$

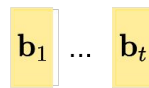
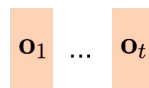
Action-related embedding learning

Action sequence
(*ex.* $y(s) = [1, 1, 1, 2]$)

a_1, a_1, a_1, a_2

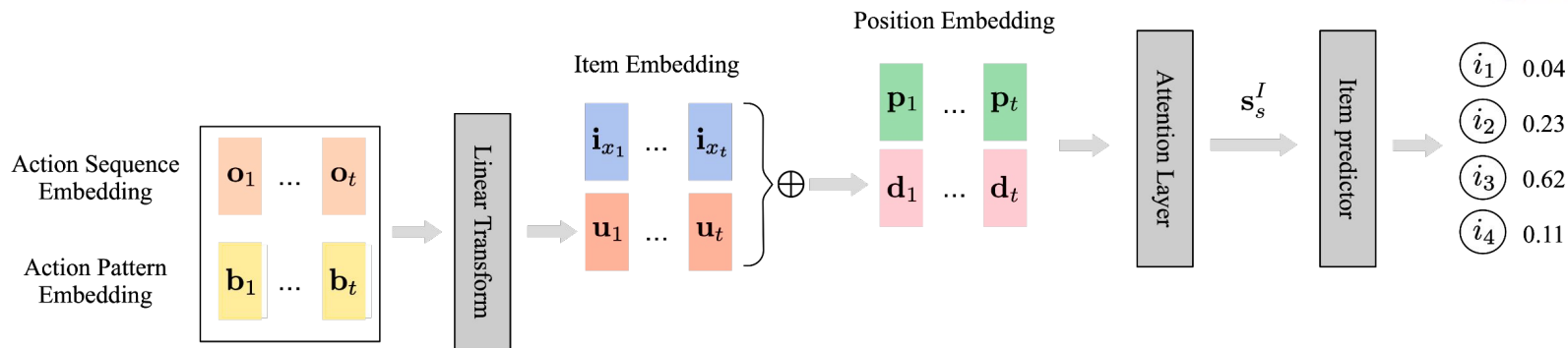
Item-wise
action-pattern sequence

b_1, b_2, b_3, b_4
 $([a_1], [a_1], [a_1], [a_1, a_2])$



(Final hidden states)

Action-aware Session Representation Learning for Next-item Prediction



1. Combine action embeddings

$$\mathbf{u}_k = \text{dropout}(\text{RELU}(\mathbf{o}_k \parallel \mathbf{b}_k) \mathbf{U}_4 + \mathbf{q}_3)$$

$$\mathbf{d}_k = \mathbf{i}_{x_k} + \mathbf{u}_k$$

2. Learn attention weights

$$\alpha_k = \mathbf{q}_5^T \sigma(\mathbf{W}_{12} \mathbf{h}_k + \mathbf{W}_{13} \mathbf{s}' + \mathbf{q}_6)$$

$$\mathbf{h}_k = \tanh(\mathbf{d}_k \parallel \mathbf{p}_{t-k+1} \mathbf{U}_5 + \mathbf{q}_4)$$

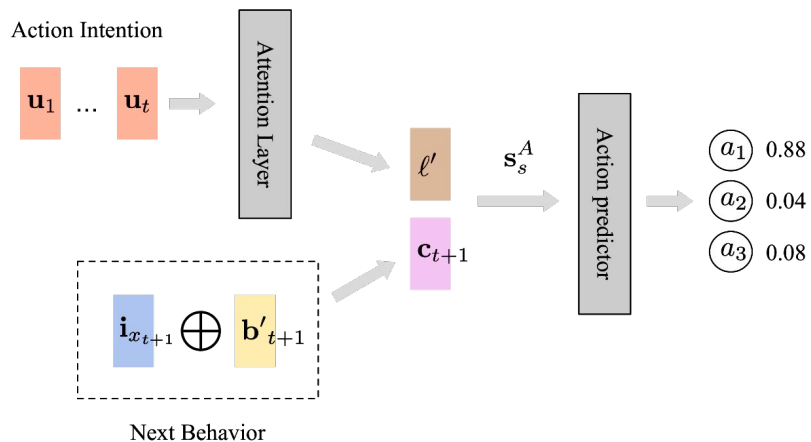
$$\mathbf{s}' = \sum_{i=1}^t \mathbf{d}_k / t$$

3. Compute item scores

$$\mathbf{s}_s^I = \sum_{i=1}^t \alpha_k \mathbf{d}_k$$

$$\hat{y}_j^I = \text{softmax}(\mathbf{s}_s^I \mathbf{i}_i)$$

Conditional Multiplex Behavior Session Modeling for Next-action Prediction



$\mathbf{i}_{x_{t+1}}$: predicted next item embedding

\mathbf{b}'_{t+1} : action pattern embedding

1. Learn session-level action intention

$$\mathbf{u}_k = \text{RELU}((\mathbf{o}_k \parallel \mathbf{b}_k) \mathbf{U}_6 + \mathbf{q}_7)$$

$$\beta_k = \mathbf{q}_8^T \sigma(\mathbf{W}_{14} \mathbf{u}_k + \mathbf{W}_{15} \mathbf{c}_{t+1} + \mathbf{q}_9)$$

$$\ell' = \sum_{k=1}^t \beta_k \mathbf{u}_k$$

2. Combine action intention & next behavior

$$\mathbf{c}_{t+1} = \mathbf{i}_{x_{t+1}} + \mathbf{b}'_{t+1} \quad \mathbf{s}_s^A = \mathbf{U}_6(\ell' \parallel \mathbf{c}_{t+1})$$

3. Compute action scores

$$\hat{y}_j^A = \text{softmax}(\mathbf{s}_s^A \mathbf{a}_j)$$

Multi-task Learning

- ⊙ Total loss: combination of the cross entropy loss of the two predictors

$$\mathcal{L}_{action} = - \sum_{i=1}^{|\mathcal{I}|} y_i^I \log(\hat{y}_i^I) + (1 - y_i^I) \log(1 - \hat{y}_i^I)$$
$$\mathcal{L}_{action} = - \sum_{i=1}^{|\mathcal{A}|} \omega_i y_i^A \log(\hat{y}_i^A) + (1 - y_i^A) \log(1 - \hat{y}_i^A)$$

$$\mathcal{L}_{joint} = \mathcal{L}_{item} + \lambda \mathcal{L}_{action}$$

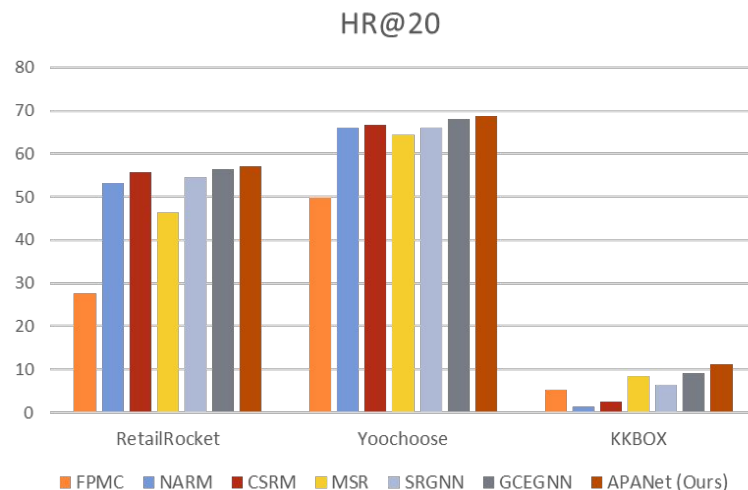
- ⊙ Control parameters

ω_i : penalty weight of each type of action a_i

λ : multi-task learning weight

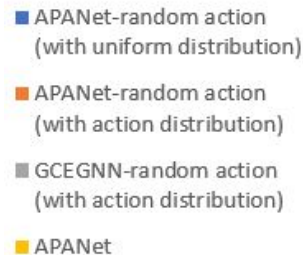
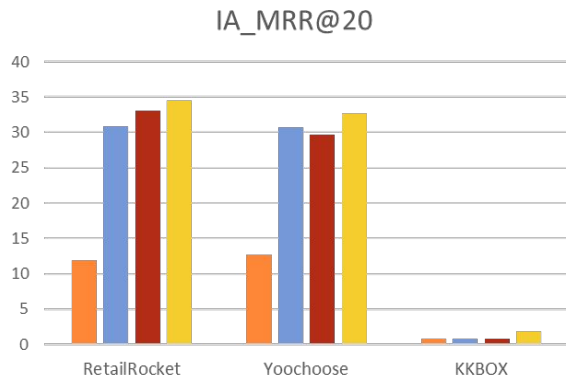
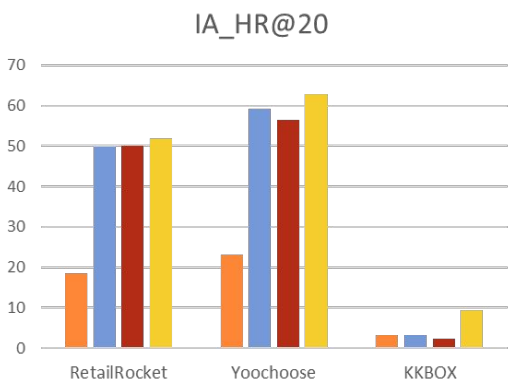
Experiment Results: Next-Item Prediction

- ⊙ APANet outperforms baseline models on 3 datasets
- ⊙ All methods predict badly on KKBOX datasets due to its different data properties
- ⊙ APANet achieves the most significant improvements for KKBOX, yielding 21.88% of HR@20 (KKBOX has 8 action types)



Experiment Results: Next-Item and Next-Action Prediction

- Next-best prediction is considered correct if **both the item and the action** match the ground truth
- The proposed APANet outperforms the compared methods (especially on KKBOX dataset)



Ablation study: Effectiveness of APANet's components

- Overall performance decline after discarding any individual component of the model, indicating the significance of these components in the design

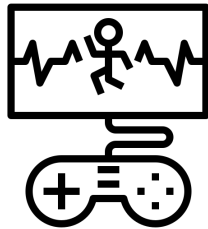
Model setting	KKBOX				RetailRocket			
	HR@20	MRR@20	IA_HR@20	IA_MRR@20	HR@20	MRR@20	IA_HR@20	IA_MRR@20
(1) W/o act_pattern_emb	9.813	2.065	6.853	1.395	55.211	37.933	49.886	30.634
(2) W/o act_seq_emb	10.201	2.411	8.830	1.864	56.419	38.025	51.137	33.240
(3) W/o pos_emb	7.430	2.040	5.149	1.079	54.905	37.881	49.183	30.271
(4) Next-action predictor	11.876	2.879	–	–	55.420	38.127	–	–
APANet	11.183	3.182	9.446	1.881	57.001	38.735	51.790	34.475

APANet Applications

For users:

Enhancing customer experience

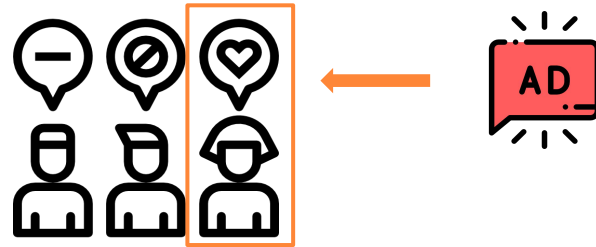
- Predicting user's next move
- E.g. gaming, shopping



For company:

Precision marketing

- Identifying potential customers
- Difference advertising



Conclusions and Future Work

◎ Conclusions

- Propose a action-aware network multi-behavior recommender (APANet) that could predict not only the next-item but the next-action
- Design item-wise action pattern reformulation and a conditional network for action-intent generation
- Demonstrate the superior performance of the model by extensive experiments and ablation studies

◎ Future work

- Introduce more side information such as item features
- Explore the importance to user intent of different action types
- Exploring interpretability aspects

Thank you!

